LC88F52H0A

CMOS IC
FROM 512K byte, RAM 24K byte on-chip

16-bit 1-chip Microcontroller

ON Semiconductor®

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Overview

The LC88F52H0A is a 16-bit microcomputer that, centered around an Xstromy16 CPU, integrates on a single chip a number of hardware features such as 512K-byte flash ROM (onboard programmable), 24K-byte RAM, eight 16-bit timers, a base timer serving as a time-of-day clock,, a real time clock, two synchronous SIO interfaces with automatic transmission capability, two single master I^{2}C/synchronous SIO interface, a slave I^{2}C/synchronous SIO interface, four asynchronous SIO (UART) interfaces, a 16-channel 12-bit resolution AD converter, 8bit resolution DA converter, four multifrequency 12-bit PWM modules, a watchdog timer, a system clock frequency divider, a 59-source (32 modules) 14-vector interrupt feature, and on-chip debugger feature.

Features

■Xstromy16 CPU
- 4G-byte address space
- General-purpose registers: 16 bits × 16registers

■Flash ROM
- Capable of onboard programming with a wide range of voltage levels (3.0 to 5.5V).
- Block-erasable in 512 or 1K byte units.
- Data written in 2-byte units.
- 524288 × 8 bits

■RAM
- 24576 × 8 bits

* This product is licensed from Silicon Storage Technology, Inc. (USA).

■Minimum instruction cycle time (tCYC)
- 83.3 ns (12MHz) V_{DD} = 4.5 to 5.5V
- 107 ns (9.3MHz) V_{DD} = 3.0 to 5.5V
- 500 ns (2MHz) V_{DD} = 2.5 to 5.5V

■Ports
- Normal withstand voltage I/O ports
  Ports whose I/O direction can be designated in 1 bit units : 86 (P0n P1n, P2n, P3n, P4n, P5n, P6n, P7n, PAn PB0
  to PB6, PC2, PD0 to PD5)
- Oscillation/normal withstand voltage I/O ports   : 4 (PC0, PC1, PC3, PC4)
- Reset pins   : 1 (RESB)
- TEST pins   : 1 (TEST)
- Power pins   : 8 (V_{SS}1 to 4, V_{DD}1 to 4)

■Timers
- Timer 0: 16-bit timer that supports PWM/toggle outputs
  1) 5-bit prescaler
  2) 8-bit PWM × 2, 8-bit timer + 8-bit PWM mode selectable
  3) Clock source selectable from system clock, OSC0, OSC1, and internal RC oscillator
- Timer 1: 16-bit timer with capture registers
  1) 5-bit prescaler
  2) May be divided into 2 channels of 8-bit timer
  3) Clock source selectable from system clock, OSC0, OSC1, and internal RC oscillator
- Timer 2: 16-bit timer with capture registers
  1) 4-bit prescaler
  2) May be divided into 2 channels of 8-bit timer
  3) Clock source selectable from system clock, OSC0, OSC1, and external events
- Timer 3: 16-bit timer that supports PWM/toggle outputs
  1) 8-bit prescaler
  2) 8-bit timer × 2ch or 8-bit timer + 8-bit PWM mode selectable
  3) Clock source selectable from system clock, OSC0, OSC1, and external events
- Timer 4: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 0
- Timer 5: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 0
- Timer 6: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 1
- Timer 7: 16-bit timer that supports toggle outputs
  1) Clock source selectable from system clock and prescaler 1
  * Prescaler 0 and 1 are consisted of 4 bits and can choose their clock source from OSC0 or OSC1.
- Base timer
  1) Clock may be selected from OSC0 (32.768kHz crystal oscillator) and frequency-divided output of system clock.
  2) Interrupts can be generated in 7 timing schemes.

■Real time clock
  1) Calender with Jan. 1, 2000 to Dec.31, 2799 including automatic leap year calculation function.
  2) Consisted of Independent second- minute-hour-day-month-year-century counters.
  3) Programmable count-clock calibration function.

■Serial interfaces

- SIO0: 8-bit synchronous SIO
  1) LSB first/MSB first mode selectable
  2) Supports data communication with a data length of 8 bits or less (1 to 8 bits specifiable)
  3) Built-in 8-bit baudrate generator (4 tCYC to 512 tCYC transfer clocks)
  4) Continuous/automatic data transmission (9- to 32768-bit units specifiable)
  5) Interval function (intervals specifiable in 0 to 64 tSCK units)
  6) Wakeup function
- SIO1: 8-bit synchronous SIO
  1) LSB first/MSB first mode selectable
  2) Supports data communication with a data length of 8 bits or less (1 to 8 bits specifiable)
  3) Built-in 8-bit baudrate generator (4 tCYC to 512 tCYC transfer clocks)
  4) Continuous/automatic data transmission (9- to 32768-bit units specifiable)
  5) Interval function (intervals specifiable in 0 to 64 tSCK units)
  6) Wakeup function
- SMIIC0: Single master I^2C/8-bit synchronous SIO
  Mode 0: Single-master mode communication
  Mode 1: Synchronous 8-bit serial I/O (MSB first)
- SMIIC1: Single master I^2C/8-bit synchronous SIO
  Mode 0: Single-master mode communication
  Mode 1: Synchronous 8-bit serial I/O (MSB first)
- SLIIC0: Slave I^2C/8-bit synchronous SIO
  Mode 0: I^2C slave mode communication
  Mode 1: Synchronous 8-bit serial I/O (MSB first)
     Note: usable only with the external clock source
- UART0
  1) Data length   : 8 bits (LSB first)
  2) Start bits   : 1 bit
  3) Stop bits   : 1 bit
  4) Parity bits   : None/even parity/odd parity
  5) Transfer rate   : 4/8 cycle
  6) Baudrate source clock: P07 input signal used as a 1 cycle signal (T0PWMH can be used as a clock source) or Timer 4 cycle.
  7) Full duplex communication
     Note: The "cycle" refers to one period of the baudrate clock source.
- UART2
  1) Data length   : 8 bits (LSB first)
  2) Start bits   : 1 bit
  3) Stop bits   : 1/2 bit
  4) Parity bits   : None/even parity/odd parity
  5) Transfer rate   : 8 to 4096 cycle
  6) Baudrate source clock : System clock/OSC0/OSC1/P26 input signal
  7) Wakeup function
  8) Full duplex communication
     Note: The "cycle" refers to one period of the baudrate clock source.
- UART3
  1) Data length   : 8 bits (LSB first)
  2) Start bits   : 1 bit
  3) Stop bits   : 1/2 bit
  4) Parity bits   : None/even parity/odd parity
  5) Transfer rate   : 8 to 4096 cycle
  6) Baudrate source clock: System clock/OSC0/OSC1/P36 input signal
  7) Wakeup function
  8) Full duplex communication
     Note: The "cycle" refers to one period of the baudrate clock source.

- UART4
  1) Data length   : 8 bits (LSB first)
  2) Start bits   : 1 bit
  3) Stop bits   : 1/2 bit
  4) Parity bits   : None/even parity/odd parity
  5) Transfer rate   : 8 to 4096 cycle
  6) Baudrate source clock: System clock/OSC0/OSC1/P37 input signal
  7) Wakeup function
  8) Full duplex communication
     Note: The "cycle" refers to one period of the baudrate clock source.

■AD converter
  1) 12/8 bits resolution selectable
  2) Analog input: 16 channels
  3) Comparator mode
  4) Automatic reference voltage generation

■DA converter
  1) 8 bits resolution
  2) 2 converters built-in
  3) Able to choose output pins

■PWM
  - PWM0: Multifrequency 12-bit PWM × 2 channels (PWM00 and PWM01)
    1) 2-channel pairs controlled independently of one another
    2) Clock source selectable from system clock or OSC1
    3) 8-bit prescaler: TPWMR0=(prescaler value + 1) × clock period
    4) 8-bit fundamental wave PWM generator circuit + 4-bit additional pulse generator circuit
    5) Fundamental wave PWM mode
       Fundamental wave period: 16 TPWMR0 to 256 TPWMR0
       High pulse width   : 0 to (Fundamental wave period - TPWMR0)
    6) Fundamental wave + additional pulse mode
       Fundamental wave period: 16 TPWMR0 to 256 TPWMR0
       Overall period   : Fundamental wave period × 16
       High pulse width   : 0 to (Fundamental wave period - TPWMR0)
  - PWM1: Multifrequency 12-bit PWM × 2 channels (PWM10 and PWM11)
    1) 2-channel pairs controlled independently of one another
    2) Clock source selectable from system clock or OSC1
    3) 8-bit prescaler: TPWMR1=(prescaler value + 1) × clock period
    4) 8-bit fundamental wave PWM generator circuit + 4-bit additional pulse generator circuit
    5) Fundamental wave PWM mode
       Fundamental wave period: 16 TPWMR1 to 256 TPWMR1
       High pulse width   : 0 to (Fundamental wave period - TPWMR1)
    6) Fundamental wave + additional pulse mode
       Fundamental wave period: 16 TPWMR1 to 256 TPWMR1
       Overall period   : Fundamental wave period × 16
       High pulse width   : 0 to(Fundamental wave period - TPWMR1)

■Watchdog timer
  1) Driven by the base timer + internal watchdog timer dedicated counter
  2) Interrupt or reset mode selectable

■Interrupts (peripheral function)
- 59 sources (32 modules), 14 vector addresses
  1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
  2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Interrupt Source
1	08000H	Watchdog timer (1)
2	08004H	Base timer (2)
3	08008H	Timer 0 (2)
4	0800CH	INT0 (1)
5	08014H	INT1 (1)
6	08018H	INT2 (1)/timer 1 (2)/UART2 (4)
7	0801CH	INT3 (1)/timer 2 (4)/SMIIC0 (1)/SLIIC1 (1)
8	08020H	INT4 (1)/timer 3 (2)
9	08024H	INT5 (1)/timer 4 (1)/SIO1 (2)
10	0802CH	PWM0 (1)/SMIIC1(1)
11	08030H	ADC (1)/timer 5 (1)
12	08034H	INT6 (1)/timer 6 (1)/UART 3 (4)
13	08038H	INT7 (1)/SIO0 (2)/SIO0(2)/USRT4 (4)
14	0803CH	Port 0 (3)/Port 5 (8)/RTC (1)

- 3 priority levels selectable.
- Of interrupts of the same level, the one with the smallest vector address takes precedence.
- A number enclosed in parentheses denotes the number of sources.

■Subroutine Stack: 24K-byte RAM area
- Subroutine calls that automatically save PSW, interrupt vector calls: 6 bytes
- Subroutine calls that do not automatically save PSW: 4 bytes

■Multiplication/division instructions
- 16 bits × 16 bits (18 tCYC execution time)
- 16 bits ÷ 16 bits (18 to 19 tCYC execution time)
- 32 bits ÷ 16 bits (18 to 19 tCYC execution time)

■Oscillator circuits
- RC oscillator circuit (internal): For system clock
- CF oscillator circuit (built-in Rf circuit): For system clock (OSC1)
- VCO oscillator circuit: For system clock (OSC1)
- Crystal oscillator circuit (built-in Rf circuit): For low-speed system clock (OSC0)
- SLRC oscillator circuit (internal): For system clock (In the case of exception processing)

■System clock divider function
- Can run on low current.
- 1/1 to 1/128 of the system clock frequency can be set.

■Standby Function
- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
  1) Oscillation is not halted automatically.
  2) Released by a system reset or occurrence of an interrupt.
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
  1) OSC1, RC and OSC0 oscillators automatically stop.
  2) There are the six ways of releasing the HOLD mode.
      (1) Setting the reset pin to the low level
      (2) Setting at least one of the INT0, INT1, INT2, INT4, INT5, INT6, and INT7 pins to the specified level
      (3) Having an interrupt source established at port 0
      (4) Having an interrupt source established at port 5
      (5) Having an interrupt established at SIO0 or SIO1
      (6) Having an interrupt established at UART2, UART3 or UART4
- HOLDX mode: Suspends instruction execution and the operation of the peripheral circuits except those which run on OSC0.
  1) OSC1 and RC oscillations automatically stop.
  2) OSC0 maintains the state that is established when the HOLDX mode is entered.
  3) There are seven ways of releasing the HOLDX mode.
      (1) Setting the reset pin to the low level
      (2) Setting at least one of the INT0, INT1, INT2, INT4, INT5, INT6, and INT7 pins to the specified level
      (3) Having an interrupt source established at port 0
      (4) Having an interrupt source established at port 5
      (5) Having an interrupt source established at the base timer circuit
      (6) Having an interrupt established at SIO0 or SIO1
      (7) Having an interrupt established at UART2, UART3 or UATR4
      .

■On-chip debugger function
- Supports software debugging with the IC mounted on the target board.
- Supports source line debugging and tracing functions, and breakpoint setting and real time display.
- Single-wire communication

■Package Form
- TQFP100(14×14): Lead-free and halogen-free type

■Development Tools
- On-chip debugger: EOCUIF1 + LC88F52H0A

■Programming board

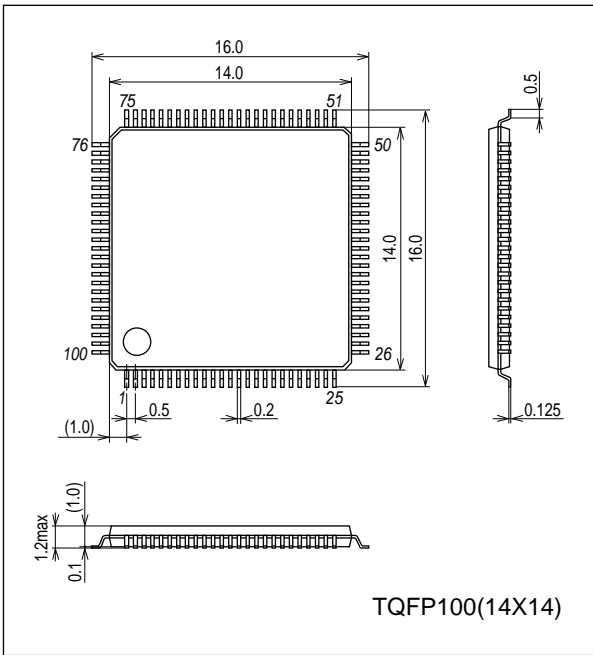| Package	Programming Board
TQFP100 (14 × 14)	W88F52TQ

■Flash Programming

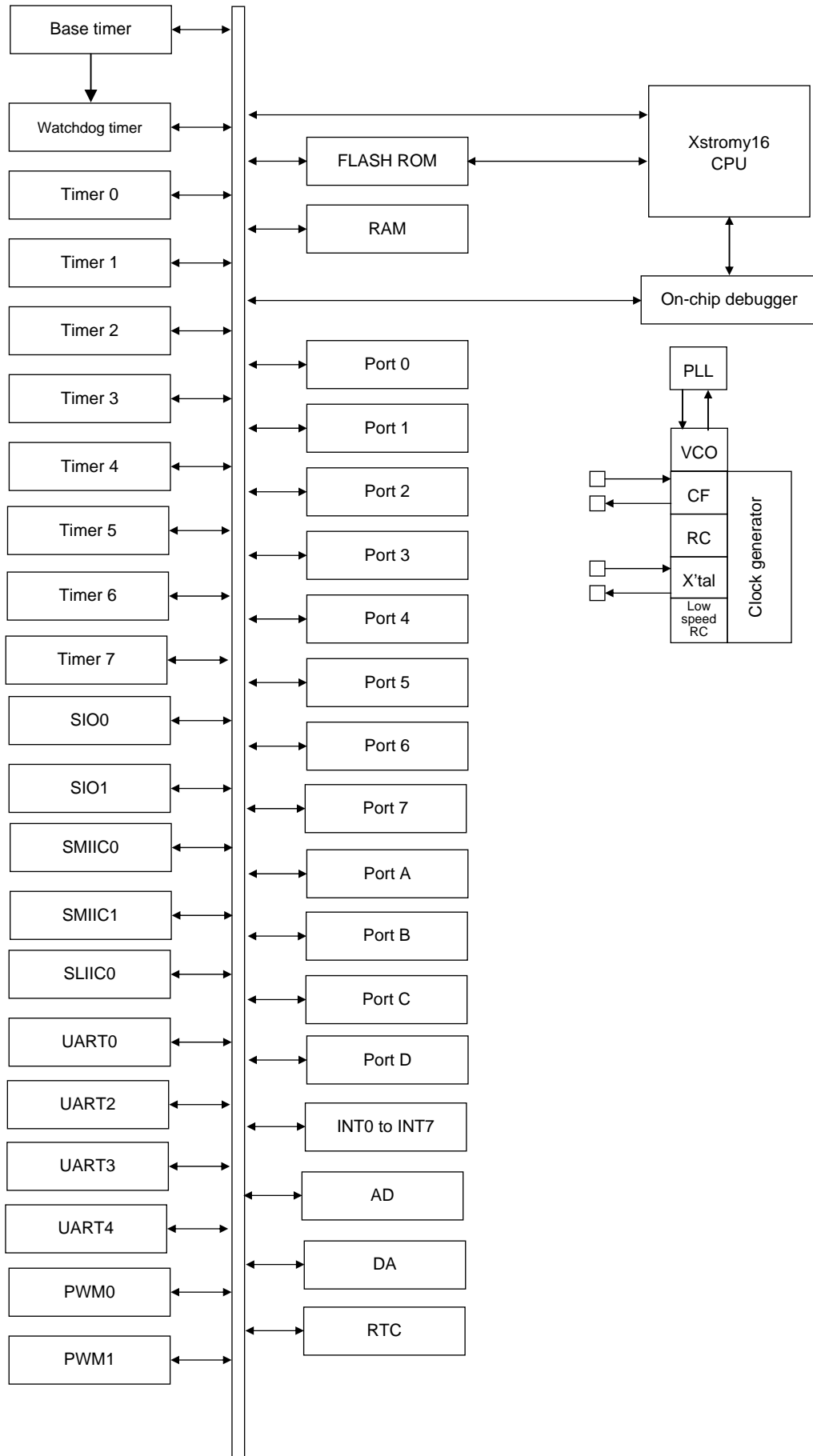| Manufacturer	Model Name	Supported Version	Device
Flash Support Group (single)	AF9708/09/09B/09C	Revision: After Rev.03.32D	88F512SN
Flash Support Group (Gang)	AF9723/23B		
	AF9833		
Our company	SKK/SKK Type-B	Application Version After 1.06 Chip Data Version After 2.22	LC88F52H0A

Package Dimensions

unit : mm (typ)
3274

TQFP100(14X14)

Pin Assignment

Top side pins (left to right, 75 to 51):
PB5/SM1DA, PB4/SM1CK, PB3/U4TX, PB2/U4RX, PB1/PWM11, PB0/PWM10, P37/T7O, P36/T6O, P35/U3TX, P34/U3RX, P33/INT3, P32/INT2, P31/INT1, P30/INT0, P07/T0PWMH/U0BRG, P06/T0PWML, P05/P05INT, P04/P04INT, P03/P0INT, P02/P0INT, P01/P0INT, P00/P0INT, VSS3, VDD3, P40/INT6

Left side pins (76 to 100):
- 76 PB6/SM1DO
- 77 P70/AN8
- 78 P71/AN9
- 79 P72/AN10
- 80 P73/AN11
- 81 P74/AN12
- 82 P75/AN13
- 83 P76/AN14
- 84 P77/AN15
- 85 VSS4
- 86 VDD4
- 87 PA0
- 88 PA1
- 89 PA2
- 90 PA3
- 91 PA4/SL0CK
- 92 PA5/SL0DA
- 93 PA6/SL0DO
- 94 PA7
- 95 PC2/FILT
- 96 P50/P5INT0
- 97 P51/P5INT1
- 98 P52/P5INT2
- 99 P53/P5INT3
- 100 P54/P5INT4

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Right side pins (50 to 26):
- 50 P41/INT7
- 49 P42
- 48 P43/SO1
- 47 P44/SI1/SB1
- 46 P45/SCK1
- 45 P46/PWM00
- 44 P47/PWM01
- 43 P27
- 42 P26/T5O
- 41 P25/T4O
- 40 P24/SM0DO
- 39 P23/SM0DA
- 38 P22/SM0CK
- 37 VDD2
- 36 VSS2
- 35 P21/INT5
- 34 P20/INT4
- 33 PD5/DA22
- 32 PD4/DA21
- 31 PD3/DA20
- 30 PD2/DA02
- 29 PD1/DA01
- 28 PD0/DA00
- 27 P17/U2TX
- 26 P16/U2RX

Bottom side pins (left to right, 1 to 25):
P55/P5INT5, P56/P5INT6, P57/P5INT7, TEST, RESB, PC0/XT1, PC1/XT2, VSS1, PC3/CF1, PC4/VCOT/CF2, VDD1, P60/AN0, P61/AN1, P62/AN2, P63/AN3, P64/AN4, P65/AN5, P66/AN6, P67/AN7, P10/SO0, P11/SI0/SB0, P12/SCK0, P13/U0TX, P14/T3OL/U0RX, P15/T3OH

Top view

TQFP100 (14×14) (Lead-free and halogen-free type)

System Block Diagram

```
Base timer ↔ [bus]

Watchdog timer ↔ [bus]          FLASH ROM ↔ [bus] ←→ Xstromy16 CPU

Timer 0 ↔                        RAM ↔

Timer 1 ↔                                        On-chip debugger ←

Timer 2 ↔                        Port 0 ↔                 PLL

Timer 3 ↔                        Port 1 ↔                 VCO

Timer 4 ↔                        Port 2 ↔                 CF

Timer 5 ↔                        Port 3 ↔                 RC     Clock generator

Timer 6 ↔                        Port 4 ↔                 X'tal

Timer 7 ↔                        Port 5 ↔                 Low speed RC

SIO0 ↔                           Port 6 ↔

SIO1 ↔                           Port 7 ↔

SMIIC0 ↔                         Port A ↔

SMIIC1 ↔                         Port B ↔

SLIIC0 ↔                         Port C ↔

UART0 ↔                          Port D ↔

UART2 ↔                          INT0 to INT7 ↔

UART3 ↔                          AD ↔

UART4 ↔                          DA ↔

PWM0 ↔                           RTC ↔

PWM1 ↔
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Pin Description

Pin Name	I/O	Description
$V_{SS}1$, $V_{SS}2$, $V_{SS}3$, $V_{SS}4$	-	- Power sources
$V_{DD}1$, $V_{DD}2$, $V_{DD}3$, $V_{DD}4$	-	+ Power sources

Port 0
 	
P00 to P07
	I/O	• 8-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• HOLD release input (P00 to P03, P04, P05)
		• Port 0 interrupt input (P00 to P03, P04, P05)
		• Pin functions
		  P06: Timer 0L output
		  P07: Timer 0L output/UART0 clock input

Port 1
 	
P10 to P17
	I/O	• 8-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Pin functions
		  P10: SIO0 data output
		  P11: SIO0 data input/pulse input/output
		  P12: SIO0 clock input/output
		  P13: UART0 transmit
		  P14: Timer 3L output/UART0 receive
		  P15: Timer 3H output
		  P16: UART2 receive
		  P17: UART2 transmit

Port 2
 	
P20 to P27
	I/O	• 8-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Pin functions
		  P20: INT4 input/HOLD release input/timer 3 event input/timer 2L capture input/timer 2H capture input
		  P21: INT5 input/HOLD release input/timer 3 event input/timer 2L capture input/timer 2H capture input
		  P22: SMIIC0 clock input/output
		  P23: SMIIC0 bus input/output/data input
		  P24: SMIIC0 data output (used in 3-wire SIO mode)
		  P25: Timer 4 output
		  P26: Timer 5 output
		  Interrupt acknowledge type
		  INT4, INT5: H level, L level, H edge, L edge, both edges

Port 3
 	
P30 to P37
	I/O	• 8-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Pin functions
		  P30: INT0 input/HOLD release/timer 2L capture input
		  P31: INT1 input/HOLD release/timer 2H capture input
		  P32: INT2 input/HOLD release/timer 2 event input/timer 2L capture input
		  P33: INT3 input/HOLD release/timer 2 event input/timer 2H capture input
		  P34: UART3 receive
		  P35: UART3 transmit
		  P36: Timer 6 output
		  P37: Timer 7 output
		  Interrupt acknowledge type
		  INT0 to INT3: H level, L level, H edge, L edge, both edges

Continued from preceding page.

| Pin Name	I/O	Description

Port 4
P40 to P47
	I/O	• 8-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Pin functions
		  P40: INT6 input/HOLD release input
		  P41: INT7 input/HOLD release input
		  P43: SIO1 data output
		  P44: SIO1 data input/bus input/output
		  P45: SIO1 clock input/output
		  P46: PWM00 output
		  P47: PWM01 output
		  Interrupt acknowledge type
		  INT6, INT7: H level, L level, H edge, L edge, both edges

Port 6 P60 to P67	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions AN0 (P60) to AN7 (P67): AD converter input port
Port 7 P70 to P77	I/O	• 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1 bit units • Pin functions AN8 (P70) to AN15 (P77): AD converter input port

Port A
PA0 to PA7
	I/O	• 8-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Multiplexed pin functions
		  PA4: SLIIC0 clock input
		  PA5: SLIIC0 bus input/output/data input
		  PA6: SLIIC0 data output (used in 3-wire SIO mode)

Port B
PB0 to PB6
	I/O	• 7-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Multiplexed pin functions
		  PB0: PWM10 output
		  PB1: PWM11 output
		  PB2: UART4 receive
		  PB3: UART4 transmit
		  PB4: SMIIC1 clock input/output
		  PB5: SMIIC1 bus input/output/data input
		  PB6: SMIIC1 data output (used in 3-wire SIO mode)

Port C
PC0 to PC4
	I/O	• 5-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units (PC2)
		• Pin functions
		  PC0: 32.768 kHz crystal oscillator input
		  PC1: 32.768 kHz crystal oscillator output
		  PC2: FILT
		  PC3: Ceramic oscillator input
		  PC4: Ceramic oscillator output/VCO output

Port D
PD0 to PD5
	I/O	• 6-bit I/O port
		• I/O specifiable in 1-bit units
		• Pull-up resistors can be turned on and off in 1 bit units
		• Multiplexed pin functions
		  PD0: DA00 output
		  PD1: DA01 output
		  PD2: DA02 output
		  PD3: DA10 output
		  PD4: DA11 output
		  PD5: DA12 output

TEST	I/O	• TEST pin • Used to communicate with on-chip debugger. • Connects an external 100kΩ pull-down resistor.
RESB	I	Reset pin

Port Output Types

The table below lists the types of port outputs and the presence/absence of a pull-up resistor.
Data can be read into any input port even if it is in the output mode.

Port Name	Option Selected in Units of	Output Type	Pull-up Resistor
P00 to P07	1 bit	CMOS	Programmable
P10 to P17 P20 to P27 P30 to P37 P40 to P47 P50 to P57 P60 to P67 P70 to P77 PA0 to PA7 PB0 to PB6		Able to program special functions' output type from CMOS output or N-channel open drain	
P60 to P67 P70 to p77 PD0 to PD5 PC2		CMOS	
PC0	-	N-channel open drain (32.768kHz crystal oscillator input)	None
PC1	-	N-channel open drain (32.768kHz crystal oscillator output)	None
PC3	-	CMOS (ceramic oscillator input)	None
PC4	-	CMOS (ceramic oscillator output)	None

* Make the following connection to minimize the noise input to the $V_{DD}1$ pin and prolong the backup time.
  Be sure to electrically short the $V_{SS}1$, $V_{SS}2$, $V_{SS}3$ and VSS4 pins.

Example 1: When data is being backed up in the HOLD mode, the H level signals to the output ports are fed by the backup capacitors.
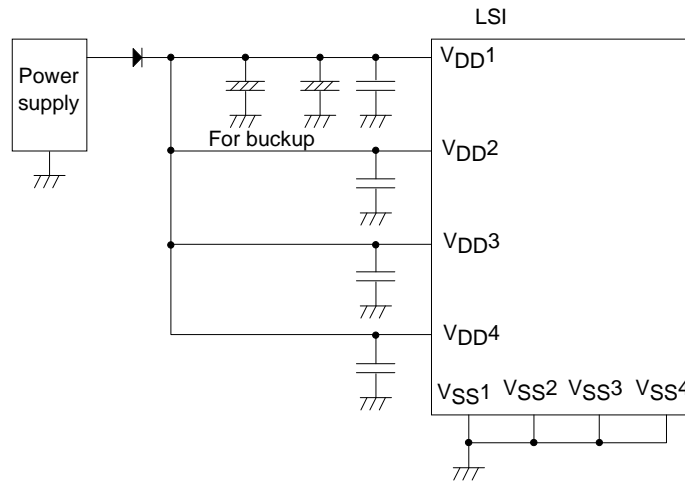
Example 2: When data is being backed up in the HOLD mode, the H level output at any ports is not sustained and is unpredictable.
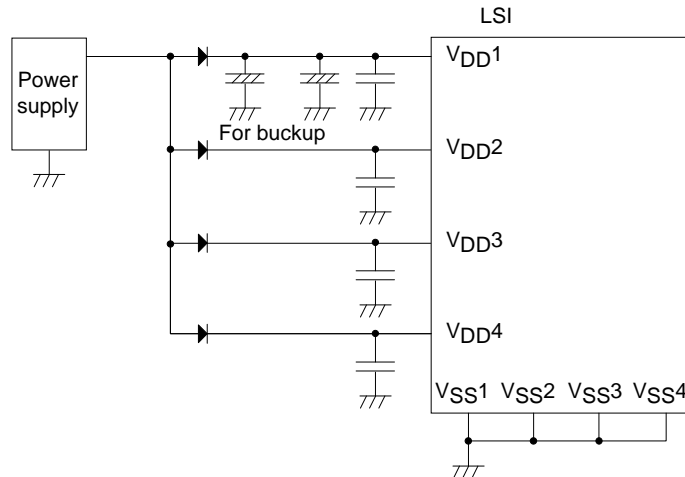
Absolute Maximum Ratings at $Ta = 25°C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter		Symbol	Applicable Pin /Remarks	Conditions	Specification				
					V_{DD}[V]	min	typ	max	unit
Maximum supply voltage		V_{DD} max	$V_{DD}1$, $V_{DD}2$, $V_{DD}3$, $V_{DD}4$	$V_{DD}1=V_{DD}2=V_{DD}3=V_{DD}4$		-0.3		+6.5	V
Input voltage		$V_I(1)$	RESB			-0.3		V_{DD} +0.3	
Input/output voltage		$V_{IO}(1)$	Ports 0, 1, 2 Ports 3, 4, 5 Ports 6, 7 Ports A, B, C, D			-0.3		V_{DD} +0.3	
High level output current	Peak output current	IOPH(1)	Ports 0, 1, 2, 3 P40 to P45 Ports 7, A, D PB2 to PB6	CMOS output selected Per applicable pin		-10			mA
		IOPH(2)	P46, P47 PB0, PB1	Per applicable pin		-20			
		IOPH(3)	Port 5, 6 PC0 to PC4	Per applicable pin		-5			
	Average output current (Note 1-1)	IOMH(1)	Ports 0, 1, 2, 3 P40 to P45 Ports 5, 6, 7, A PB2 to PB6 Ports D	CMOS output selected Per applicable pin		-7.5			
		IOMH(2)	P46, P47 PB0, PB1	Per applicable pin		-10			
		IOMH(3)	Port 5, 6 PC0 to PC4	Per applicable pin		-3			
	Total output current	ΣIOAH(1)	Pprts 5 PC0 to PC4	Total of currents at applicable pins		-15			
		ΣIOAH(2)	Port 6	Total of currents at applicable pins		-15			
		ΣIOAH(3)	Port 5, 6 PC0 to PC4	Total of currents at applicable pins		-20			
		ΣIOAH(4)	Ports 1,D1 P20 to P21	Total of currents at applicable pins		-25			
		ΣIOAH(5)	P22 to P27	Total of currents at applicable pins		-25			
		ΣIOAH(6)	Ports 1, 2, D	Total of currents at applicable pins		-45			
		ΣIOAH(7)	Ports 4	Total of currents at applicable pins		-25			
		ΣIOAH(8)	Ports 0, 3	Total of currents at applicable pins		-25			
		ΣIOAH(9)	Ports 0, 3, 4	Total of currents at applicable pins		-45			
		ΣIOAH(10)	Ports B, 7	Total of currents at applicable pins		-25			
		ΣIOAH(11)	Ports A	Total of currents at applicable pins		-25			
		ΣIOAH(12)	Ports 7, A, B	Total of currents at applicable pins		-45			

Note 1-1: Average output current refers to the average of output currents measured for a period of 100ms.

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Parameter		Symbol	Applicable Pin /Remarks	Conditions	Specification				
					V_{DD}[V]	min	typ	max	unit
Low level output current	Peak output current	IOPL(1)	Ports 0, 1, 3, 4 Ports 7, A, B P20, P21, P24 to P27 PA0 to PA4, PA6, PA7 PB0 to PB4, PB6, PB7	Per applicable pin				20	mA
		IOPL(2)	P22, P23 PA4, PA5 PB4, PB5	Per applicable pin				25	
		IOPL(3)	Ports 5, 6 PC0 to PC4	Per applicable pin				10	
	Average output current (Note 1-1)	IOML(1)	Ports 0, 1, 3, 4 Ports 7, A, B P20, P21, P24 to P27 PA0 to PA4, PA6, PA7 PB0 to PB4, PB6, PB7	Per applicable pin				15	
		IOML(2)	P22, P23 PA4, PA5 PB4, PB5	Per applicable pin				20	
		IOML(3)	Ports 5, 6 PC0 to PC4	Per applicable pin				7.5	
	Total output current	ΣIOAL(1)	Ports 5 PC0 to PC2	Total of currents at applicable pins				15	
		ΣIOAL(2)	Port 6 PC3 to PC4	Total of currents at applicable pins				15	
		ΣIOAL(3)	Port 5, 6 PC0 to PC4	Total of currents at applicable pins				20	
		ΣIOAL(4)	Ports 1, D P20, P21	Total of currents at applicable pins				45	
		ΣIOAL(5)	P22 to P27	Total of currents at applicable pins				45	
		ΣIOAL(6)	Ports 1, 2, D	Total of currents at applicable pins				80	
		ΣIOAL(7)	Port 4	Total of currents at applicable pins				45	
		ΣIOAL(8)	Port 0, 3	Total of currents at applicable pins				45	
		ΣIOAL(9)	Port 0, 3, 4	Total of currents at applicable pins				80	
		ΣIOAL(10)	Port 7, B	Total of currents at applicable pins				45	
		ΣIOAL(11)	Port A	Total of currents at applicable pins				45	
		ΣIOAL(12)	Port 7, A, B	Total of currents at applicable pins				80	
Allowable power dissipation		Pd max	TQFP100(14×14)	Ta=-40 to +85°C				250	mW
Operating ambient temperature		Topr				-40		+85	°C
Storage ambient temperature		Tstg				-55		+125	

Note 1-1: Average output current refers to the average of output currents measured for a period of 100ms.

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Allowable Operating Conditions at Ta = -40°C to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Operating supply voltage (Note 2-1)	V_{DD}(1)	$V_{DD}1=V_{DD}2=V_{DD}3$	0.081μs≤tCYC≤66μs		4.0		5.5	
			0.103μs≤tCYC≤66μs		3.0		5.5	
			0.490μs≤tCYC≤66μs		2.5		5.5	
Memory sustaining supply voltage	VHD	$V_{DD}1=V_{DD}2=V_{DD}3$	RAM and register contents sustained in HOLD mode		2.0		5.5	
High level input voltage	V_{IH}(1)	Ports 0, 1, 2, 3, 4 Port 5, A, B		2.5 to 5.5	$0.3V_{DD}$ +0.7		V_{DD}	V
	V_{IH}(2)	Ports 6, 7, PC2		2.5 to 5.5	$0.3V_{DD}$ +0.7		V_{DD}	
	V_{IH}(3)	RESB PC0, PC1, PC3, PC4		2.5 to 5.5	$0.75V_{DD}$		V_{DD}	
	V_{IH}(4)	P22, P23, PA4, PA5, PB4, PB5 I²C side		2.5 to 5.5	$0.7V_{DD}$		V_{DD}	
Low level input voltage	V_{IL}(1)	When ports 1, 2, 3, 4, 5, A and port B,		4.0 to 5.5	V_{SS}		$0.1V_{DD}$ +0.4	
	V_{IL}(2)	PnFSAn=0 Ports 0, 6, 7, PC2		2.5 to 4.0	V_{SS}		$0.2V_{DD}$	
	V_{IL}(3)	When ports 1, 2, 3, 4, 5, A and port B,		4.0 to 5.5	V_{SS}		$0.15V_{DD}$ +0.4	
	V_{IL}(4)	PnFSAn=1		2.5 to 4.0	V_{SS}		$0.2V_{DD}$	
	V_{IL}(5)	CF1, RESB PC0, PC1, PC3, PC4		2.5 to 5.5	V_{SS}		$0.25V_{DD}$	
	V_{IL}(6)	P22, P23, PA4, PA5, PB4, PB5 I²C side		2.5 to 5.5	V_{SS}		$0.3V_{DD}$	
Instruction cycle time (Note 2-2)	tCYC			4.5 to 5.5	0.081		66	μs
				2.8 to 5.5	0.122		66	
				2.5 to 5.5	0.490		66	
External system clock frequency	FEXCF(1)	CF1	• CF2 pin open • System clock frequency division ratio=1/1 • External system clock DUTY50±5%	4.5 to 5.5	0.1		12	MHz
				3.0 to 5.5	0.1		8.3	
				2.5 to 5.5	0.1		2	
			• CF2 pin open • System clock frequency division ratio=1/2	4.5 to 5.5	0.2		24	
				3.0 to 5.5	0.2		18.6	
				2.5 to 5.5	0.2		4	

Note 2-1: V_{DD}≥3.0V must be maintained when making onboard programming into flash ROM.

Note 2-2: Relationship between tCYC and oscillation frequency is 1/FmCF when frequency division ratio is 1/1 and 2/FmCF when the ratio is 1/2.

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Parameter	Symbol	Applicable Pin /Remarks	Conditions	V$_{DD}$[V]	Specification min	typ	max	unit
Oscillation frequency range (Note 2-3)	FmCF(1)	PC3 (CF1), PC4 (CF2)	12MHz ceramic oscillator mode See Fig. 1.	4.5 to 5.5		12		MHz
	FmCF(2)	PC3(CF1), PC4(CF2)	8MHz ceramic oscillator mode See Fig. 1.	3.0 to 5.5		8		
	FmCF(3)	PC3(CF1), PC4(CF2)	4MHz ceramic oscillator mode See Fig. 1.	2.5 to 5.5		4		
	FmRC		Internal RC oscillation	2.5 to 5.5	0.5	1.0	2.0	
	FmSLRC		Internal low-speed RC oscillation	2.5 to 5.5	18	30	45	kHz
	FsX'tal	XT1, XT2	32.768kHz crystal oscillator mode See Fig. 2.	2.5 to 5.5		32.768		
	FmVCO(1)		VCO oscillator When setting VC3=1 When SELDIV=0 or 1 See Fig. 9.	2.5 to 3.8	5.0		9.0	
	FmVCO(2)		VCO oscillator When setting VC3=0 When SELDIV=2 or 3 See Fig. 9.	2.5 to 3.8	5.0		12	
	FmVCO(3)		VCO oscillator When setting VC3=1 When SELDIV=0 or 1 See Fig. 9.	3.6 to 5.5	5.0		9.0	MHz
	FmVCO(4)		VCO oscillator When setting VC3=0 When SELDIV=2 or 3 See Fig. 9.	3.6 to 5.5	9.0		12	
	FmVCO(5)		VCO oscillator When OSC0=32.768KHz SELDIV setting range=0 to 3 SELDLY setting range=0 to 3	2.5 to 5.5		Note 2-4		

Note 2-3: See Tables 1 and 2 for oscillator constant values.

Note 2-4: VCO oscillation frequency = $0.032768 \times (56 \times (SELDIV+3) + SELDLY)$

Electrical Characteristics at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable/ Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
High level input current	$I_{IH}(1)$	Ports 0, 1, 2 Ports 3, 4, 5 Ports 6, 7 Ports A, B, C, D RESB	Output disabled Pull-up resistor off $V_{IN}=V_{DD}$ (Including output Tr. off leakage current)	2.5 to 5.5			1	μA
Low level input current	$I_{IL}(1)$	Ports 0, 1, 2 Ports 3, 4, 5 Ports 6, 7 Ports A, B, C, D RESB	Output disabled Pull-up resistor off $V_{IN}=V_{SS}$ (Including output Tr. off leakage current)	2.5 to 5.5	-1			
High level output voltage	$V_{OH}(1)$	Ports 0, 1, 2, 3 Ports 4, A, D P40 to P45 PB2 to PB6	I_{OH}=-1.0mA	4.5 to 5.5	V_{DD}-1			V
	$V_{OH}(2)$		I_{OH}=-0.4mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(3)$		I_{OH}=-0.2mA	2.5 to 5.5	V_{DD}-0.4			
	$V_{OH}(4)$	Port 5, 6 PC2	I_{OH}=-0.4mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(5)$		I_{OH}=-0.2mA	2.5 to 5.5	V_{DD}-0.4			
	$V_{OH}(6)$	P46, P47 PB0, PB1	I_{OH}=-10mA	4.5 to 5.5	V_{DD}-1.5			
	$V_{OH}(7)$		I_{OH}=-1.6mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(8)$		I_{OH}=-1.0mA	2.5 to 5.5	V_{DD}-0.4			
	$V_{OH}(9)$	PC0, PC1, PC3, PC4,	I_{OH}=-1.0mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(10)$		I_{OH}=-0.4mA	2.5 to 5.5	V_{DD}-0.4			
Low level output voltage	$V_{OL}(1)$	Ports 0, 1, 3, 4 Ports 7, D	I_{OL}=10mA	4.5 to 5.5			1.5	V
	$V_{OL}(2)$	P20 to P21, P24 to P27	I_{OL}=1.6mA	3.0 to 5.5			0.4	
	$V_{OL}(3)$	PA0 to PA3 PA6 to PA7 PB0 to PB3, PB6	I_{OL}=1.0mA	2.5 to 5.5			0.4	
	$V_{OL}(4)$	P22, P23, PA4, PA5, PB4, PB5	I_{OL}=11mA	4.5 to 5.5			1.5	
	$V_{OL}(5)$		I_{OL}=3.0mA	3.0 to 5.5			0.4	
	$V_{OL}(6)$		I_{OL}=1.3mA	2.5 to 5.5			0.4	
	$V_{OL}(7)$	Ports 5, 6 PC2	I_{OL}=1.6mA	3.0 to 5.5			0.4	
	$V_{OL}(8)$		I_{OL}=1.0mA	2.5 to 5.5			0.4	
	$V_{OL}(9)$	PC0, PC1, PC3, PC4	I_{OL}=1.0mA	3.0 to 5.5			0.4	
	$V_{OL}(10)$		I_{OL}=0.4mA	2.5 to 5.5			0.4	
Pull-up resistor	Rpu(1)	Ports 0, 1, 2, 3 Ports 4, 5, 6, 7	V_{OH}=0.9V_{DD}	4.5 to 5.5	15	35	80	kΩ
	Rpu(2)	Ports A, B, D, PC2		2.5 to 4.5	18	55	150	
Hysteresis voltage	VHYS	RESB When ports 1, 2, 3, 4, A PnFSAn=1		2.5 to 5.5		0.1V_{DD}		V
Pin capacitance	CP	All pins	Pins other than that under test $V_{IN}=V_{SS}$ f=1MHz Ta=25°C	2.5 to 5.5		10		pF

Serial I/O Characteristics at $Ta = -40$ to $+85°C$, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$
Serial I/O Characteristics (Wakeup Function Disabled) (Note 4-1-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(1)	SCK0(P12)	• See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(1)				2			
		High level pulse width	tSCKH(1)				2			
			tSCKHA(1)		• Automatic communication mode • See Fig. 6.		6			
			tSCKHBSY(1a)		• Automatic communication mode • See Fig. 6.		23			
			tSCKHBSY(1b)		• Mode other than automatic communication mode • See Fig. 6.		4			
	Output clock	Period	tSCK(2)	SCK0(P12)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			tSCK
		Low level pulse width	tSCKL(2)					1/2		
		High level pulse width	tSCKH(2)					1/2		
			tSCKHA(2)		• Automatic communication mode • CMOS output selected • See Fig. 6.		6			tCYC
			tSCKHBSY(2a)		• Automatic communication mode • CMOS output selected • See Fig. 6.		4		23	
			tSCKHBSY(2b)		• Mode other than automatic communication mode • See Fig. 6.		4			
Serial input		Data setup time	tsDI(1)	SI0(P11), SB0(P11)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			
		Data hold time	thDI(1)				0.03			
Serial output	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	• (Note 4-1-2)	2.5 to 5.5			1tCYC +0.05	μs
	Output clock		tdDO(2)		• (Note 4-1-2)				1tCYC +0.05	

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig. 6.

SIO0 Serial Input/Output Characteristics (Wakeup Function Enabled) (Note 4-2-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification			unit
							min	typ	max	
Serial clock	Input clock	Period	tSCK(3)	SCK0 (P12)	• See Fig. 6.	2.5 to 5.5	2			tCYC
		Low level pulse width	tSCKL(3)				1			
		High level pulse width	tSCKH(3)				1			
			tSCKHBSY(3)				2			
Serial input		Data setup time	tsDI(2)	SI0 (P11), SB0 (P11)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			μs
		Data hold time	thDI(2)				0.03			
Serial output	Input clock	Output delay time	tdD0(3)	SO0 (P10), SB0 (P11)	• (Note 4-2-2)	2.5 to 5.5			1tCYC +0.05	

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-2-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig.6.

SIO1 Serial Input/Output Characteristics (Wakeup Function Disabled) (Note 4-3-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	Specification				
						V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(4)	SCK1(P45)	• See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(4)				2			
		High level pulse width	tSCKH(4)				2			
			tSCKHA(4)		• Automatic communication mode • See Fig. 6.		6			
			tSCKHBSY(4a)		• Automatic communication mode • See Fig. 6.		23			
			tSCKHBSY(4b)		• Mode other than automatic communication mode • See Fig. 6.		4			
	Output clock	Period	tSCK(5)	SCK1(P45)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			
		Low level pulse width	tSCKL(5)					1/2		tSCK
		High level pulse width	tSCKH(5)					1/2		
			tSCKHA(5)		• Automatic communication mode • CMOS output selected • See Fig. 6.		6			tCYC
			tSCKHBSY(5a)		• Automatic communication mode • CMOS output selected • See Fig. 6.		4		23	
			tSCKHBSY(5b)		• Mode other than automatic communication mode • See Fig. 6.		4			
Serial input		Data setup time	tsDI(3)	SI1(P44), SB1(P44)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
		Data hold time	thDI(3)				0.03			
Serial output	Input clock	Output delay time	tdD0(4)	SO1(P43), SB1(P44)	• (Note 4-3-2)	2.5 to 5.5			1tCYC +0.05	µs
	Output clock		tdDO(5)		• (Note 4-3-2)				1tCYC +0.05	

Note 4-3-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-3-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig. 6.

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SIO1 Serial Input/Output Characteristics (Wakeup Function Enabled) (Note 4-4-1)

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V$_{DD}$[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(6)	SCK1(P45)	• See Fig. 6.	2.5 to 5.5	2			tCYC
		Low level pulse width	tSCKL(6)				1			
		High level pulse width	tSCKH(6)				1			
			tSCKHBSY(6)				2			
Serial input		Data setup time	tsDI(4)	SI1(P44), SB1(P44)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			μs
		Data hold time	thDI(4)				0.03			
Serial output	Input clock	Output delay time	tdD0(6)	SO1(P43), SB1(P44)	• (Note 4-4-2)	2.5 to 5.5			1tCYC +0.05	

Note 4-4-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-4-2: Specified with respect to the falling edge of SIOCLK. Specified as the interval up to the time an output change begins in the open drain output mode. See Fig. 6.

SMIIC0 Simple SIO Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V$_{DD}$[V]	min	typ	max	unit
Serial clock	Input clock	Period	tSCK(7)	SM0CK(P22)	See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(7)				2			
		High level pulse width	tSCKH(7)				2			
	Output clock	Period	tSCK(8)	SM0CK(P22)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			tSCK
		Low level pulse width	tSCKL(8)					1/2		
		High level pulse width	tSCKH(8)					1/2		
Serial input		Data setup time	tsDI(5)	SM0DA(P23)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			μs
		Data hold time	thDI(5)				0.03			
Serial output		Output delay time	tdD0(7)	SM0DO(P24), SM0DA(P23)	• Specified with respect to falling edge of SIOCLK • Specified as interval up to time when output state starts changing. • See Fig. 6.	2.5 to 5.5			1tCYC +0.05	

Note 4-5-1: These specifications are theoretical values. Add margin depending on its use.

SMIIC0 I²C Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions		Specification			
						V_{DD}[V]	min	typ	max	unit
Clock	Input clock	Period	tSCL	SM0CK(P22)	• See Fig. 8.	2.5 to 5.5	5			Tfilt
		Low level pulse width	tSCLL				2.5			
		High level pulse width	tSCLH				2			
	Output clock	Period	tSCLx	SM0CK(P22)	• Specified as interval up to time when output state starts changing.	2.5 to 5.5	10			tSCL
		Low level pulse width	tSCLLx					1/2		
		High level pulse width	tSCLHx					1/2		
SM0CK and SM0DA pins input spike suppression time			tsp	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5			1	Tfilt
Bus release time between start and stop	Input		tBUF	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	2.5			Tfilt
	Output		tBUFx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			μs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			
Start/restart condition hold time	Input		tHD;STA	SM0CK(P22) SM0DA(P23)	• When SMIIC register control bit, I²CSHDS=0 • See Fig. 8.	2.5 to 5.5	2.0			Tfilt
					• When SMIIC register control bit, I²CSHDS=1 • See Fig. 8.		2.5			
	Output		tHD;STAx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.1			μs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.0			
Restart condition setup time	Input		tSU;STA	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output		tSU;STAx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			μs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			

Continued from preceding page

Parameter		Symbol	Applicable Pin/Remarks	Conditions	Specification				
					V$_{DD}$[V]	min	typ	max	unit
Stop condition setup time	Input	tSU;STO	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output	tSU;STOx	SM0CK(P22) SM0DA(P23)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.9			μs
				• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.1			
Data hold time	Input	tHD;DAT	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	0			Tfilt
	Output	tHD;DATx	SM0CK(P22) SM0DA(P23)	• Specified as interval up to time when output state starts changing.		1		1.5	
Data setup time	Input	tSU;DAT	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5	1			Tfilt
	Output	tSU;DATx	SM0CK(P22) SM0DA(P23)	• Specified as interval up to time when output state starts changing.		1tSCL -1.5Tfilt			
SM0CK and SM0DA pins fall time	Input	tF	SM0CK(P22) SM0DA(P23)	• See Fig. 8.	2.5 to 5.5			300	ns
	Output	tF	SM0CK (P22) SM0DA (P23)	• When SMIIC register control bits, PSLW=1, P5V=1	5	20 +0.1Cb		250	
				• When SMIIC register control bits, PSLW=1, P5V=0	3	20 +0.1Cb		250	
				• SM0CK, SM0DA port output FAST mode • Cb≤400pF	3 to 5.5			100	

Note 4-6-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-6-2: The value of Tfilt is determined by the values of the register SMIC0BRG, bits 7 and 6 (BRP1, BRP0) and the system clock frequency.

BRP1	BRP0	Tfilt
0	0	tCYC×1
0	1	tCYC×2
1	0	tCYC×3
1	1	tCYC×4

Set bits (BPR1, BPR0) so that the value of Tfilt falls between the following range:
250ns ≥ Tfilt >140ns

Note 4-6-3: Cb represents the total loads (in pF) connected to the bus pins.   Cb ≤ 400pF

Note 4-6-4: The standard clock mode refers to a mode that is entered by configuring SMIC0BRG as follows:
250ns ≥ Tfilt >140ns
BRDQ (bit5) = 1
SCL frequency setting ≤ 100kHz
The high-speed clock mode refers to a mode that is entered by configuring SMIC0BRG as follows:
250ns ≥ Tfilt >140ns
BRDQ (bit5) = 0
SCL frequency setting ≤ 400kHz

SMIIC1 Simple SIO Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	Specification			unit
							min	typ	max	
Serial clock	Input clock	Period	tSCK(7)	SM1CK(PB4)	See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(7)				2			
		High level pulse width	tSCKH(7)				2			
	Output clock	Period	tSCK(8)	SM1CK(PB4)	• CMOS output selected • See Fig. 6.	2.5 to 5.5	4			tSCK
		Low level pulse width	tSCKL(8)					1/2		
		High level pulse width	tSCKH(8)						1/2	
Serial input		Data setup time	tsDI(5)	SM1DA(PB5)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			µs
		Data hold time	thDI(5)				0.03			
Serial output		Output delay time	tdD0(7)	SM1DO(PB6), SM1DA(PB5)	• Specified with respect to falling edge of SIOCLK • Specified as interval up to time when output state starts changing. • See Fig. 6.	2.5 to 5.5			1tCYC +0.05	

Note 4-7-1: These specifications are theoretical values. Add margin depending on its use.

SMIIC1 I²C Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_{DD}[V]	min	typ	max	unit
Clock	Input clock	Period	tSCL	SM1CK(PB4)	• See Fig. 8.	2.5 to 5.5	5			Tfilt
		Low level pulse width	tSCLL				2.5			
		High level pulse width	tSCLH				2			
	Output clock	Period	tSCLx	SM1CK(PB4)	• Specified as interval up to time when output state starts changing.	2.5 to 5.5	10			tSCL
		Low level pulse width	tSCLLx					1/2		
		High level pulse width	tSCLHx					1/2		
SM0CK and SM0DA pins input spike suppression time			tsp	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5			1	Tfilt
Bus release time between start and stop	Input		tBUF	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	2.5			Tfilt
	Output		tBUFx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			
Start/restart condition hold time	Input		tHD;STA	SM1CK(PB4) SM1DA(PB5)	• When SMIIC register control bit, I²CSHDS=0 • See Fig. 8.	2.5 to 5.5	2.0			Tfilt
					• When SMIIC register control bit, I²CSHDS=1 • See Fig. 8.		2.5			
	Output		tHD;STAx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.1			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.0			
Restart condition setup time	Input		tSU;STA	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output		tSU;STAx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		5.5			µs
					• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.6			

Continued from preceding page

Parameter		Symbol	Applicable Pin/Remarks	Conditions	Specification				
					V_DD[V]	min	typ	max	unit
Stop condition setup time	Input	tSU;STO	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
	Output	tSU;STOx	SM1CK(PB4) SM1DA(PB5)	• Standard clock mode • Specified as interval up to time when output state starts changing.		4.9			µs
				• High-speed clock mode • Specified as interval up to time when output state starts changing.		1.1			
Data hold time	Input	tHD;DAT	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	0			Tfilt
	Output	tHD;DATx	SM1CK(PB4) SM1DA(PB5)	• Specified as interval up to time when output state starts changing.		1		1.5	
Data setup time	Input	tSU;DAT	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5	1			Tfilt
	Output	tSU;DATx	SM1CK(PB4) SM1DA(PB5)	• Specified as interval up to time when output state starts changing.		1tSCL -1.5Tfilt			
SM0CK and SM0DA pins fall time	Input	tF	SM1CK(PB4) SM1DA(PB5)	• See Fig. 8.	2.5 to 5.5			300	ns
	Output	tF	SM1CK(PB4) SM1DA(PB5)	• When SMIIC register control bits PSLW=1, P5V=1	5	20 +0.1Cb		250	
				• When SMIIC register control bits PSLW=1, P5V=0	3	20 +0.1Cb		250	
				• SM0CK, SM0DA port output FAST mode • Cb≤400pF	3 to 5.5			100	

Note 4-8-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-8-2: The value of Tfilt is determined by the values of the register SMIC1BRG, bits 7 and 6 (BRP1, BRP0) and the system clock frequency.

BRP1	BRP0	Tfilt
0	0	tCYC×1
0	1	tCYC×2
1	0	tCYC×3
1	1	tCYC×4

Set bits (BPR1, BPR0) so that the value of Tfilt falls between the following range:

250ns ≥ Tfilt > 140ns

Note 4-8-3: Cb represents the total loads (in pF) connected to the bus pins.   Cb ≤ 400pF

Note 4-8-4: The standard clock mode refers to a mode that is entered by configuring SMIC1BRG as follows:

250ns ≥ Tfilt > 140ns

BRDQ (bit5) = 1

SCL frequency setting ≤ 100kHz

The high-speed clock mode refers to a mode that is entered by configuring SMIC1BRG as follows:

250ns ≥ Tfilt > 140ns

BRDQ (bit5) = 0

SCL frequency setting ≤ 400kHz

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SLIIC0 Simple SIO Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V$_{DD}$[V]	Specification			
							min	typ	max	unit
Serial clock	Input clock	Period	tSCK(9)	SL0CK(PA4)	See Fig. 6.	2.5 to 5.5	4			tCYC
		Low level pulse width	tSCKL(9)				2			
		High level pulse width	tSCKH(9)				2			
Serial input		Data setup time	tsDI(7)	SL0DA(PA5)	• Specified with respect to rising edge of SIOCLK • See Fig. 6.	2.5 to 5.5	0.03			μs
		Data hold time	thDI(7)				0.03			
Serial output		Output delay time	tdD0(9)	SL0DO(PA6), SL0DA(PA5)	• Specified with respect to falling edge of SIOCLK • Specified as interval up to time when output state starts changing. • See Fig. 6.	2.5 to 5.5			1tCYC +0.05	

Note 4-9-1: These specifications are theoretical values. Add margin depending on its use.

SLIIC1 I²C Mode Input/Output Characteristics

Parameter			Symbol	Applicable Pin/Remarks	Conditions	V_DD[V]	min	typ	max	unit
Clock	Input clock	Period	tSCL	SL0CK(PA4)	• See Fig. 8.	2.5 to 5.5	5			Tfilt
		Low level pulse width	tSCLL				2.5			
		High level pulse width	tSCLH				2			
SL0CK and SL0DA pins input spike suppression time			tsp	SL0CK(PA4) SL0DA(PA5)	• See Fig. 8.	2.5 to 5.5			1	Tfilt
Bus release time between start and stop	Input		tBUF	SL0CK(PA4) SL0DA(PA5)	• See Fig. 8.	2.5 to 5.5	2.5			Tfilt
Start/restart condition hold time	Input		tHD;STA	SL0CK(PA4) SL0DA(PA5)	• When SMIIC register control bit, I²CSHDS=0 • See Fig. 8.	2.5 to 5.5	2.0			Tfilt
					• When SMIIC register control bit I²CSHDS=1 • See Fig. 8.		2.5			
Restart condition setup time	Input		tSU;STA	SL0CK(PA4) SL0DA(PA5)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
Stop condition setup time	Input		tSU;STO	SL0CK(PA4) SL0DA(PA5)	• See Fig. 8.	2.5 to 5.5	1.0			Tfilt
Data hold time	Input		tHD;DAT	SL0CK(PA4) SL0DA(PA5)	• See Fig. 8.	2.5 to 5.5	0			Tfilt
	Output		tHD;DATx	SL0CK(PA4) SL0DA(PA5)	• Specified as interval up to time when output state starts changing.		1		1.5	
Data setup time	Input		tSU;DAT	SL0CK(PA4) SL0DA(PA5)	• See Fig. 8.	2.5 to 5.5	1			Tfilt
	Output		tSU;DATx	SL0CK(PA4) SL0DA(PA5)	• Specified as interval up to time when output state starts changing.		1tSCL -1.5Tfilt			

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UART0 Operating Conditions at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Transfer rate	UBR0	U0RX(P13), U0TX(P14), U0BRG(P07)		2.5 to 5.5	4		8	tBGCYC

Note 4-9: tBGCYC denotes one cycle of the baudrate clock source.

UART2 Operating Conditions at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Transfer rate	UBR2	U2RX(P16), U2TX(P17)		2.5 to 5.5	8		4096	tBGCYC

Note 4-10: tBGCYC denotes one cycle of the baudrate clock source.

UART3 Operating Conditions at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Transfer rate	UBR3	U3RX(P34), U3TX(P35)		2.5 to 5.5	8		4096	tBGCYC

Note 4-10: tBGCYC denotes one cycle of the baudrate clock source.

UART4 Operating Conditions at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Transfer rate	UBR4	U4RX(PB2), U4TX(PB3)		2.5 to 5.5	8		4096	tBGCYC

Note 4-10: tBGCYC denotes one cycle of the baudrate clock source.

Pulse Input Conditions at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
High/low level pulse width	tPIH(1) tPIL(1)	INT0(P30), INT1(P31), INT2(P32), INT3(P33), INT4(P20), INT5(P21), INT6(P40), INT7(P41)	• Interrupt source flag can be set. • Event inputs for timers 2 and 3 are enabled.	2.5 to 5.5	2			tCYC
	tPIL(2)	RESB	Resetting is enabled.	2.5 to 5.5	10			μs

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AD Converter Characteristics at Ta = -40 to +85°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = V_{SS}4 = 0V$

12-bit AD Conversion Mode

Parameter	Symbol	Applicable Pin /Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Resolution	NAD	AN0(P60) to AN7(P67), AN8(P70) to AN15(P77)		3.0 to 5.5		12		bit
Absolute accuracy	ETAD		(Note 6-1)	3.0 to 5.5			±16	LSB
Conversion time	TCAD12		Conversion time calculated	4.5 to 5.5	27		209	µs
				3.0 to 5.5	67		209	
Analog input voltage range	VAIN			3.0 to 5.5	V_{SS}		V_{DD}	V
Analog port input current	IAINH		VAIN=V_{DD}	3.0 to 5.5			1	µA
	IAINL		VAIN=V_{SS}	3.0 to 5.5	-1			

Conversion time calculation formula: TCAD12= ((52/(AD division ratio))+2) × tCYC

8-bit AD Conversion Mode

Parameter	Symbol	Applicable Pin /Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Resolution	NAD	AN0(P60) to AN7(P67), AN8(P70) to AN15(P77)		3.0 to 5.5		8		bit
Absolute accuracy	ETAD		(Note 6-1)	3.0 to 5.5			±1.5	LSB
Conversion time	TCAD8		Conversion time calculated	4.5 to 5.5	17		129	µs
				3.0 to 5.5	42		129	
Analog input voltage range	VAIN			3.0 to 5.5	V_{SS}		V_{DD}	V
Analog port input current	IAINH		VAIN=V_{DD}	3.0 to 5.5			1	µA
	IAINL		VAIN=V_{SS}	3.0 to 5.5	-1			

Conversion time calculation formula: TCAD8= ((32/(AD division ratio))+2) × tCYC

Note 6-1: The quantization error (±1/2LSB) is excluded from the absolute accuracy.
Note 6-2: The conversion time refers to the interval from the time a conversion starting instruction is issued till the time the complete digital value against the analog input value is loaded in the result register.

The conversion time is twice the normal value when one of the following conditions occurs:
• The first AD conversion is executed in the 12-bit AD conversion mode after a system reset.
• The first AD conversion is executed after the AD conversion mode is switched from 8-bit to 12-bit AD conversion mode.

DA Converter Characteristics at Ta=-40 to+85°C, $V_{SS}1=V_{SS}2=V_{SS}3=V_{SS}4=0V$

Parameter	Symbol	Applicable Pin /Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Resolution	NDA	DA00(PD0) to DA02(PD2) DA10(PD3) to DA12(PD5)		3.0 to 5.5		8		bit
Absolute accuracy	ETDA			3.0 to 5.5			±2.0	LSB
Output resistor	DAOR			3.0 to 5.5	9.5	16.0	22.9	kΩ
Analog port output current	VDAOUT			3.0 to 5.5	V_{SS}		V_{DD}	V

Consumption Current Characteristics at Ta=-40 to +85°C, $V_{SS}1=V_{SS}2=V_{SS}3=V_{SS}4=0V$

typ: 5.0V (V_{DD}=4.5V to 5.5V), 3.3V (V_{DD}=3.0V to 4.5V, 2.2V to 4.5V)

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
Normal mode consumption current (Note 7-1)	IDDOP(1)	$V_{DD}1$ $=V_{DD}2$ $=V_{DD}3$ $=V_{DD}4$	• FmCF=12MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 12MHz • Internal RC oscillation stopped • 1/1 frequency division mode	4.5 to 5.5		10.4	19	mA
	IDDOP(2)		• FmCF=8MHz ceramic oscillator mode • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		8.50	17	
	IDDOP(3)		• System clock set to 8MHz • Internal RC oscillation stopped • 1/1 frequency division mode	3.0 to 4.5		4.91	13	
	IDDOP(4)		• FmCF=4MHz ceramic oscillator mode • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		4.02	6.1	
	IDDOP(5)		• System clock set to 4MHz • Internal RC oscillation stopped • 1/2 frequency division mode	2.5 to 4.5		2.62	4.3	
	IDDOP(6)		• FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		2.18	6.0	
	IDDOP(7)		• System clock set to internal RC oscillation • 1/1 frequency division mode	2.2 to 4.5		1.28	4.2	
	IDDOP(8)		• FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		72.9	195	μA
	IDDOP(9)		• System clock set to 32.768kHz • Internal RC oscillation stopped • 1/1 frequency division mode	2.2 to 4.5		39.8	160	
	IDDOP(10)		• FmCF=0Hz (oscillation stopped) • FmVCO=11.1MHz oscillator mode • FmX'tal=32.768kHz crystal oscillator mode • System clock set to VCO • Internal RC oscillation stopped • 1/1 frequency division mode	4.5 to 5.5		10.5	19.2	mA
	IDDOP(11)		• FmCF=0Hz (oscillation stopped) • FmVCO=7.34MHz oscillator mode • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		9.07	17.3	
	IDDOP(12)		• System clock set to VCO • Internal RC oscillation stopped • 1/1 frequency division mode	3.0 to 4.5		5.23	13.8	

Note 7-1: The consumption current value includes none of the currents that flow into the output transistor and internal pull-up resistors.

Continued from preceding page.

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				V_{DD}[V]	min	typ	max	unit
HALT mode consumption current (Note 7-1)	IDDHALT(1)	$V_{DD}1$ =$V_{DD}2$ =$V_{DD}3$ =$V_{DD}4$	• HALT mode • FmCF=12MHz ceramic mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 12MHz • Internal RC oscillation stopped • 1/1 frequency division mode	4.5 to 5.5		3.70	6.5	mA
	IDDHALT(2)		• HALT mode • FmCF=10MHz ceramic oscillator mode • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		2.60	5.0	
	IDDHALT(3)		• System clock set to 10MHz • Internal RC oscillation stopped • 1/1 frequency division mode	3.0 to 4.5		1.34	3.5	
	IDDHALT(4)		• HALT mode • FmCF=4MHz ceramic oscillator mode • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		1.08	3.1	
	IDDHALT(5)		• System clock set to 4MHz • Internal RC oscillation stopped • 1/2 frequency division mode	2.2 to 4.5		0.50	2.2	
	IDDHALT(6)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		0.53	3.0	
	IDDHALT(7)		• System clock set to internal RC oscillation • 1/1 frequency division mode	2.2 to 4.5		0.26	2.1	
	IDDHALT(8)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		27.3	145	µA
	IDDHALT(9)		• System clock set to 32.768kHz • Internal RC oscillation stopped • 1/1 frequency division mode	2.2 to 4.5		9.52	112	
	IDDHALT(10)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmVCO=11.1MHz oscillator mode • FmX'tal=32.768kHz crystal oscillator mode • System clock set to VCO • Internal RC oscillation stopped • 1/1 frequency division mode	4.5 to 5.5		4.19	6.8	mA
	IDDHALT(11)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmVCO=7.34MHz oscillator mode FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		3.18	5.5	
	IIDHALT(12)		• System clock set to VCO vInternal RC oscillation stopped • 1/1 frequency division mode	3.0 to 4.5		1.68	4.0	
HOLD mode consumption current	IDDHOLD(1)	$V_{DD}1$	HOLD mode • CF1=V_{DD} or open (external clock mode)	4.5 to 5.5		0.11	98	µA
	IDDHOLD(2)			2.5 to 4.5		0.04	72	
HOLDX mode consumption current	IDDHOLD(3)		HOLDX mode • CF1=V_{DD} or open (external clock mode) • FmX'tal=32.768kHz crystal oscillator mode	4.5 to 5.5		19.0	132	
	IDDHOLD(4)			2.5 to 4.5		4.91	90	

Note 7-1: The consumption current value includes none of the currents that flow into the output transistor and internal pull-up resistors.

F-ROM Programming Characteristics at Ta = +10°C to +55°C, $V_{SS}1=V_{SS}2=V_{SS}3=V_{SS}4=0V$

Parameter	Symbol	Applicable Pin/Remarks	Conditions	Specification				
				$V_{DD}[V]$	min	typ	max	unit
Onboard programming current	IDDFW(1)	$V_{DD}1$	• Microcontroller erase current current is excluded.	3.0 to 5.5			15	mA
Onboard programming time	tFW(1)		• 512-/1K-byte erase operation	3.0 to 5.5			30	ms
	tFW(2)		• 2-byte programming operation	3.0 to 5.5			60	µs

Power Pin Treatment Conditions 1 ($V_{DD}1$, $V_{SS}1$)

Connect capacitors that meet the following conditions between the $V_{DD}1$ and $V_{SS}1$ pins:

• Connect among the $V_{DD}1$ and $V_{SS}1$ pins and the capacitors C1 and C2 with the shortest possible lead wires,
  of the same length (L1=L1', L2=L2') wherever possible.
• Connect a large-capacity capacitor C1 and a small-capacity capacitor C2 in parallel.
  The capacitance of C2 should be approximately 0.1µF or larger.
• The $V_{DD}1$ and $V_{SS}1$ traces must be thicker than the other traces.
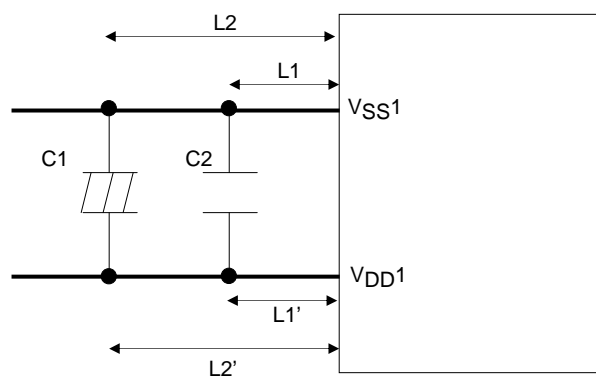
Power Pin Treatment Conditions 2 ($V_{DD}(2, 3, 4)$, $V_{SS}(2, 3, 4)$)

Connect capacitors that meet the following condition between the $V_{DD}(2, 3, 4)$ and $V_{SS}(2, 3, 4)$ pins:

• Connect among the $V_{DD}(2, 3, 4)$ and $V_{SS}(2, 3, 4)$ pins and the capacitor C3 with the shortest possible lead wires,
  of the same length (L3=L3') wherever possible.
• The capacitance of C3 should be approximately 0.1µF or larger.
• The $V_{DD}(2, 3, 4)$ and $V_{SS}(2, 3, 4)$ traces must be thicker than the other traces.
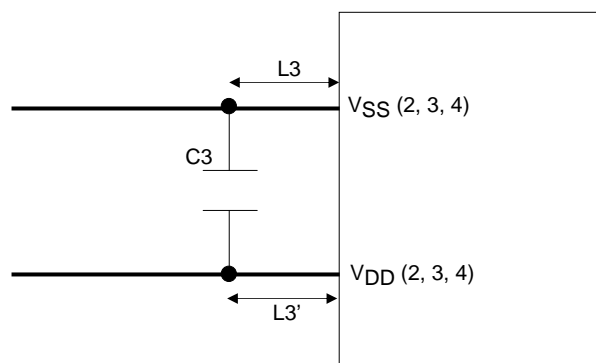
Characteristics of a Sample OSC1 System Clock Oscillation Circuit

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 1 Characteristics of a Sample Main System Clock Oscillator Circuit with a Ceramic Resonator

Nominal Frequency	Vendor Name	Resonator	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C3 [pF]	C4 [pF]	Rf [Ω]	Rd2 [Ω]		typ [ms]	max [ms]	
12MHz	MURATA	CSTCE12M0G52-R0	(10)	(10)	OPEN	470	2.4 to 5.5	0.02	0.2	C1, C2 integrated type
8MHz		CSTCE8M00G52-R0	(10)	(10)	OPEN	1k	2.3 to 5.5	0.02	0.2	C1, C2 integrated type
		CSTLS8M00G53-B0	(15)	(15)	OPEN	1k	2.5 to 5.5	0.02	0.2	C1, C2 integrated type
4MHz		CSTCR4M00G53-R0	(15)	(15)	OPEN	1.5k	2.2 to 5.5	0.02	0.2	C1, C2 integrated type
		CSTLS4M00G53-B0	(15)	(15)	OPEN	1.5k	2.3 to 5.5	0.02	0.2	C1, C2 integrated type

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after V_{DD} goes above the lower limit level of the operating voltage range (see Figure 4)

Characteristics of a Sample System Clock Oscillator Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit with a Crystal Resonator

Nominal Frequency	Vendor Name	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C3 [pF]	C4 [pF]	Rf2 [Ω]	Rd2 [Ω]		typ [s]	max [s]	
32.768kHz	EPSON TOYOCOM	MC-306	10	10	OPEN	0	2.2 to 5.5	0.8	2	Applicable CL value=7.0pF

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after the instruction for starting the subclock oscillator circuit is executed plus the time interval that is required for the oscillation to get stabilized after the HOLD mode is released (see Figure 4).

Note: The traces to and from the components that are involved in oscillation should be kept as short as possible as the oscillation characteristics are affected by their trace pattern.
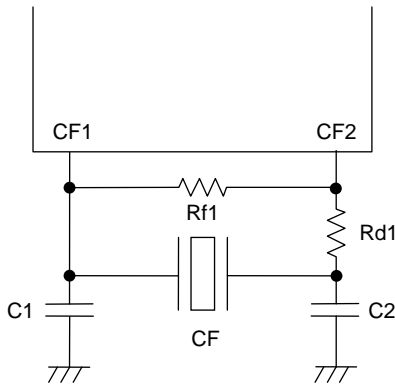
Figure 1 CF Oscillator Circuit
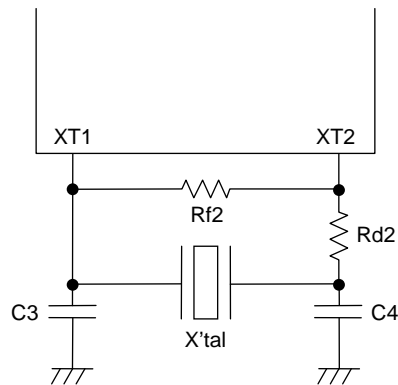
Figure 2 XT Oscillator Circuit

$0.5V_{DD}$
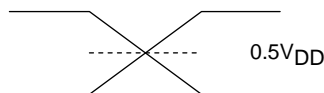
Figure 3 AC Timing Measurement Point
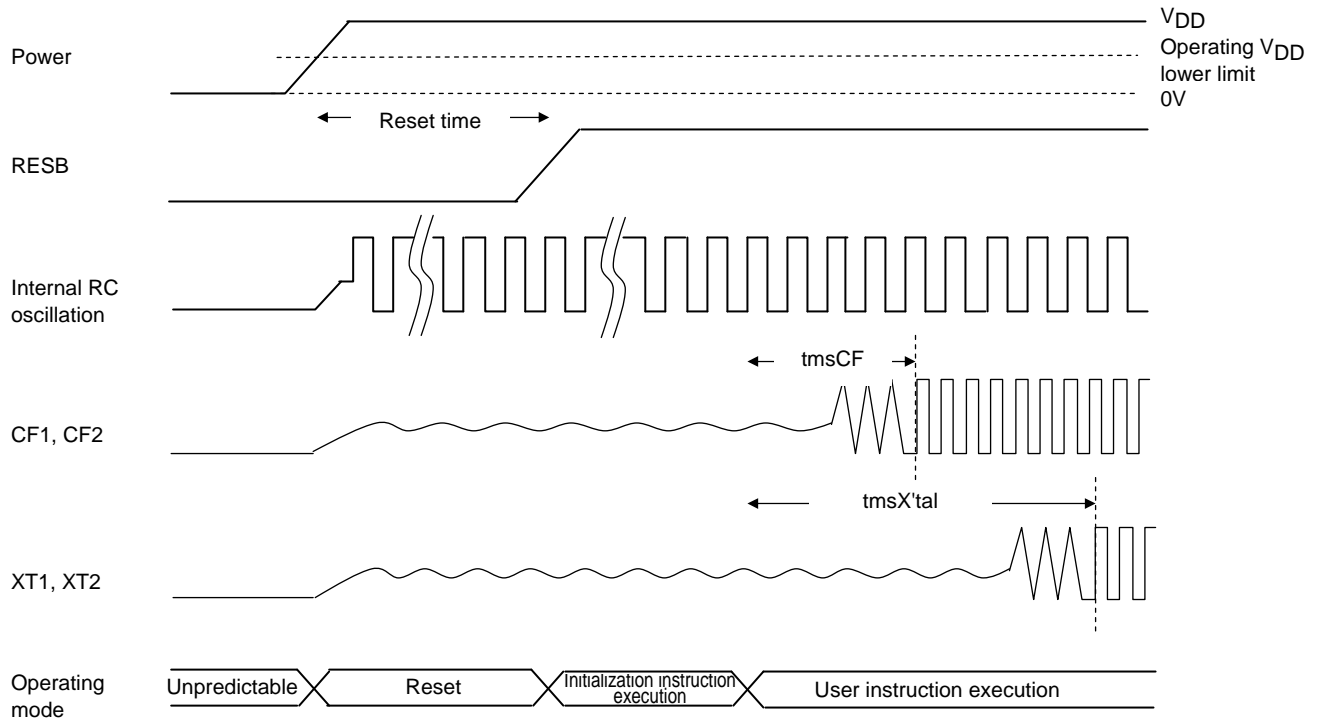
Reset Time and Oscillation Stabilization Time
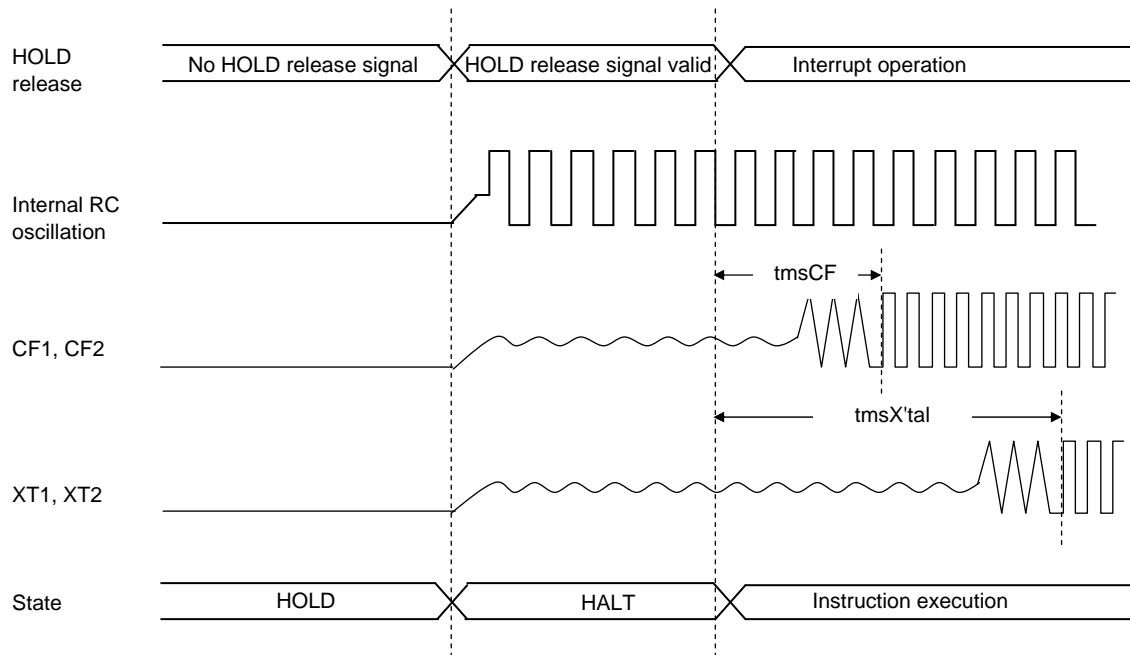
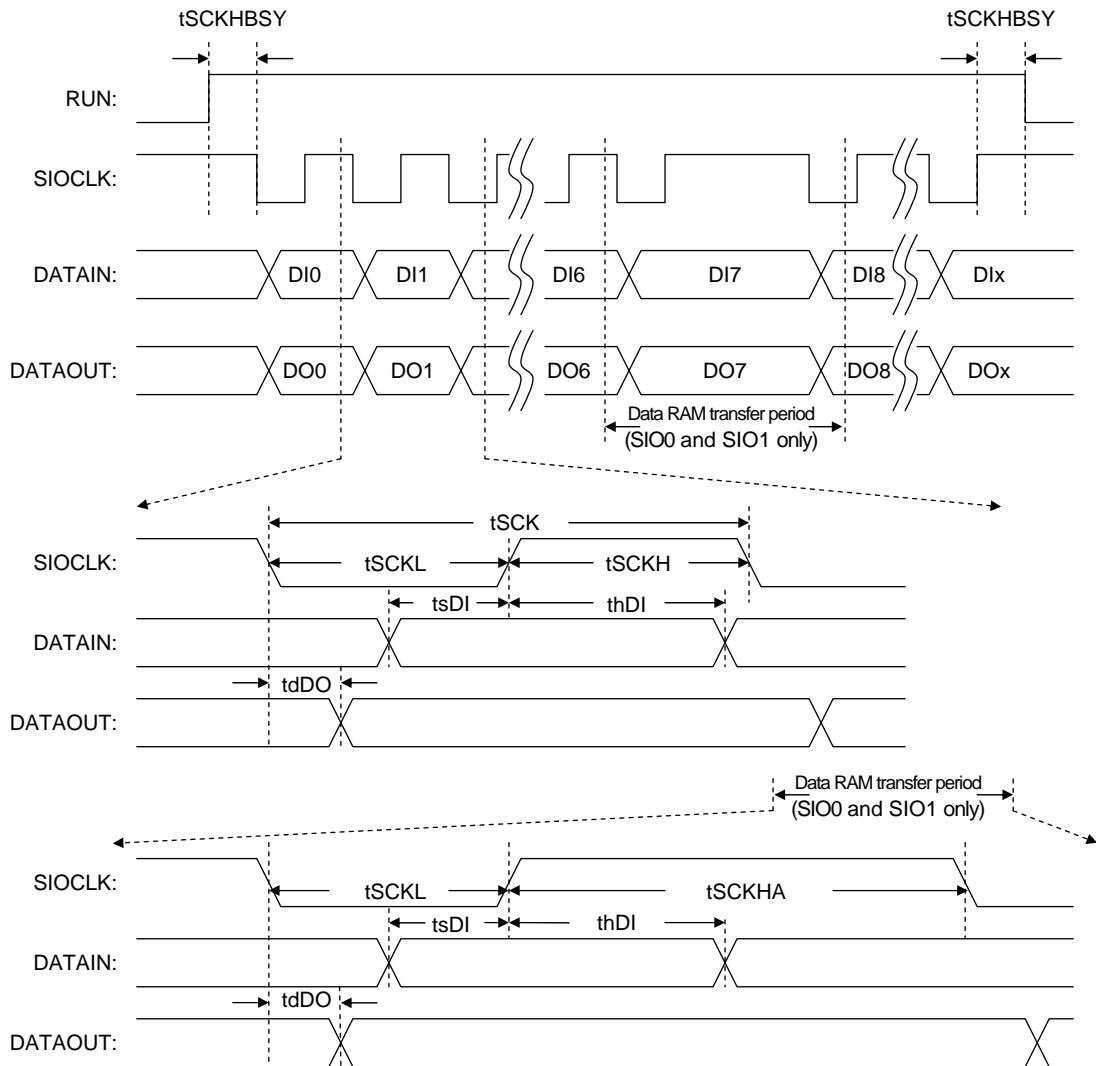HOLD Release and Oscillation Stabilization Time

Figure 4 Oscillation Stabilization Time Timing Charts

LC88F52H0A
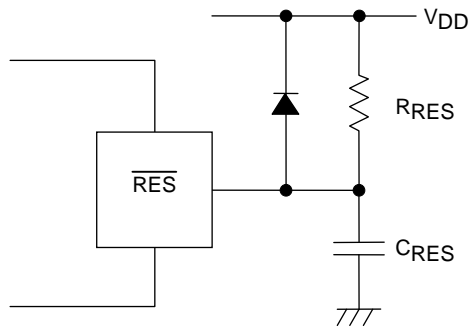
Note:
Reset signal must be present when power supply rises.
Determine the value of C_{RES} and R_{RES} so that the reset signal is present for 10μs after the supply voltage gets stabilized.

Figure 5 Reset Circuit

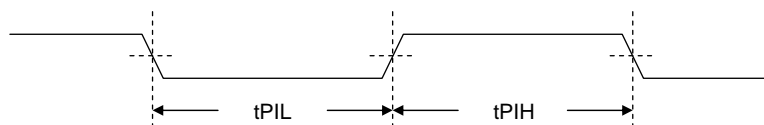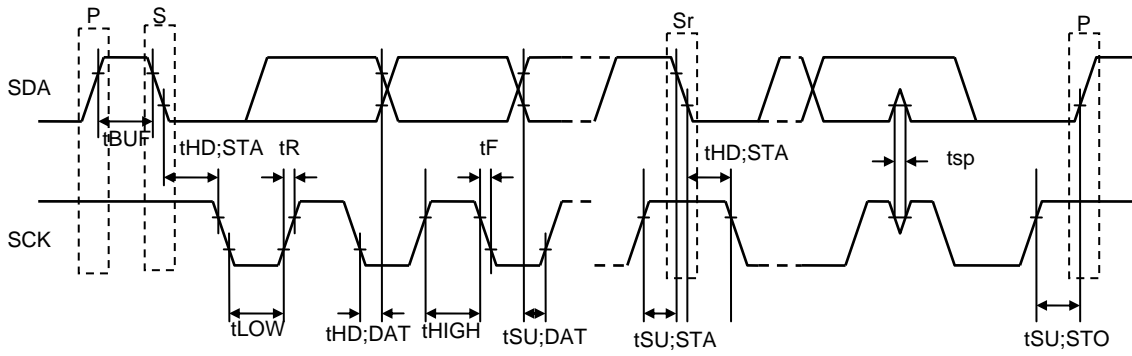*: * Remarks: DIx and DOx denote the last bits communicated; x = 0 to 32768

Figure 6 Serial I/O Waveforms

Figure 7 Pulse Input Timing Signal Waveform

S: Start condition
P: Stop condition
Sr: Restart condition

Figure 8 I^{2}C Timing
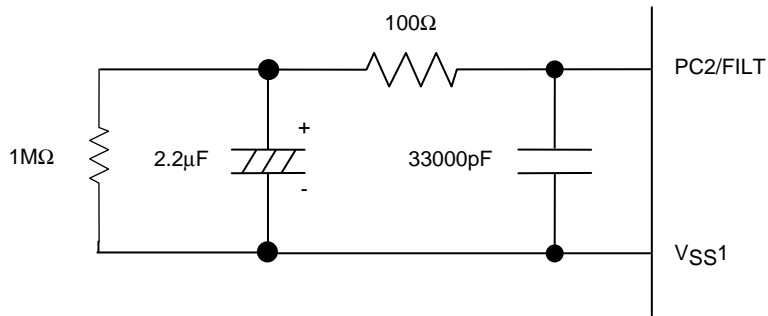
Figure 9 FILT recommended circuit
*Take at least 50ms to oscillation to stabilize after PLL is started.